# Yaesu Vx 7r Manual Book

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mobile robots navigation includes different interrelated activities i perception as obtaining and interpreting sensory information ii exploration as the strategy that guides the robot to select the next direction to go iii mapping involving the construction of a spatial representation by using the sensory information perceived iv localization as the strategy to estimate the robot position within the spatial map v path planning as the strategy to find a path towards a goal location being optimal or not and vi path execution where motor actions are determined and adapted to environmental changes the book addresses those activities by integrating results from the research work of several authors all over the world research cases are documented in 32 chapters organized within 7 categories next described

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